



ECAP Vienna Training Visit 2017

Department of Applied Geoinformatics and Spatial Planning Vítězslav Moudrý (moudry@fzp.czu.cz) Geographic Data Availability for Environmental Applications

The geographic approach

- Step 1: Ask
 - What is the problem you are trying to solve or analyze, and where is it located?

• Step 2: Acquire

• Determine the data needed to complete your analysis and ascertain where that data can be found or generated

• Step 3: Examine

• This includes visual inspection, as well as investigating how the data is organized, how well the data corresponds to other datasets, and the story of where the data came from (its metadata).

• Step 4: Analyze

 Looking at the results can help you decide whether the information is valid or useful

• Step 5: Act





Principle: Measuring physical, chemical, and biological properties of objects without direct physical contact (usually in a **raster grid**)

Types:

• Passive: Receiving the reflected and emitted radiation

 \rightarrow Aerial Photography

 \rightarrow Satellite Imagery

• Active: Transmitting electromagnetic signal

 \rightarrow Radar

 \rightarrow Laser Scanning

Any restrictions ?





Passive Remote Sensing



Active Remote Sensing

Resolution:

- Spatial
 - Satellite Imagery: 0.5 m 1 km
 - Aerial Photographs: 1 cm 5 m
- Spectral (single band, multispectral, hyperspectral)
- Temporal (Earth-orbiting, geostationary satellites)



Spectral signatures (spectral reflectance curves)





Spectral signatures of soil, vegetation and water, and spectral bands of LANDSAT 7.

http://www.seos-project.eu/modules/agriculture/agriculture-c01-s01.html

\leftarrow Increasing Frequency (v)









Aerial photographs are very suitable for detailed Surveying and mapping projects. Photogrametry Structure from motion (SfM)

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Laser Scanning:

- LiDAR ("Light Detection and Ranging") technology
- Plane or helicopter with active laser sensor
- Wavelength
 - 1000 1600nm (near-infrared for terestrial)
 - 500 600nm (blue-green for bathymetry)
- Topographic data of great detail
 - ightarrow accuracy in cm

Lidar













Example of how to combine GPS, LiDAR and passive Remote Sensing technologies to study Earth

- Greg Asner (<u>http://globalecology.stanford.edu/labs/asnerlab/</u>)
- <u>https://www.ted.com/talks/greg_asner_ecology_fr</u> om_the_air

ESA: https://earth.esa.int/web/guest/eoli

VS.

SPUTNIK: https://www.youtube.com/watch?v= RWAz 1Ck01U



http://www.esa.int/Our_Activities/Observing_the_Earth/Copernicus/Space_Component

• Copernicus <u>http://www.copernicus.eu/</u>

Copernicus, previously known as GMES (Global Monitoring for Environment and Security), is the European Programme for the establishment of a European capacity for Earth Observation.

http://land.copernicus.eu/

Sentinel

http://www.esa.int/Our Activities/Observing the Earth/C opernicus/Overview3

http://www.esa.int/Our Activities/Observing the Earth/C opernicus/Overview4

Existing datasets

Land cover/use

DEM

Land cover (LC) is defined as the biophysical material over the surface of the Earth including, among others, grass, shrubs, forests, croplands, barren, waterbodies and man-made structures

Land cover change (LCC) is the conversion from one LC category to another

LCC causes significant environmental changes at the local, regional, and global scales. For example, forest transition to agricultural land or urban expansion into croplands affects the biodiversity, soil quality, climate, and human health.

GlobCover

- <u>http://due.esrin.esa.int/page_globcover.php</u>





The aim of the project was to develop a service capable of delivering global composites and land cover maps using as input observations from the **300m MERIS sensor** on board the ENVISAT satellite mission. ESA makes available the land cover maps, which cover **2 periods**: December 2004 - June 2006 and January - December 2009.

The GlobCover 2009 dataset classifies land cover into 22 classes.

CORINE Land Cover

- <u>http://land.copernicus.eu/pan-european/corine-land-cover</u>
- <u>https://europelandcover.ourecosystem.com/interface/#layers</u>



The CORINE Land Cover (CLC) was initiated in 1985 (reference year **1990**). Updates have been produced in **2000**, **2006**, **and 2012**. It consists of an inventory of land cover in **44 classes**. CLC uses a Minimum Mapping Unit (MMU) of 25 hectares (ha) for areal phenomena and a minimum width of 100 m for linear phenomena. The time series are complemented by change layers, which highlight changes in land cover with an MMU of 5 ha.

CLC is produced by the majority of countries by visual interpretation of high resolution satellite imagery. In a few countries semi-automatic solutions are applied, using national in-situ data, satellite image processing, GIS integration and generalisation.

Classification systems come in two basic formats, *hierarchical* and *non-hierarchical*. Most systems are hierarchically structured because such a classification offers more consistency owing to its ability to accommodate different levels of information, starting with structured broad-level classes, which allow further systematic subdivision into more detailed sub-classes. At each level the defined classes are mutually exclusive.







GlobeLand30

- http://glc30.tianditu.com/
- <u>http://www.globallandcover.com/User/Login.aspx</u>





The first **30 m** resolution global land cover data set with **10 classes** and for the **year 2000 and 2010**. Over 10,000 Landsatlike satellite images are required to cover the entire Earth at 30 m resolution.

Data citation: CHEN Jun et al. (2015) Global land cover mapping at 30 m resolution: A POK-based operational approach. ISPRS Journal of Photogrammetry and Remote Sensing Volume 103, May 2015, Pages 7–27.





The mixed pixel problem: The low accuracy of land use/cover is due to mixed pixel problem, which result from the fact that the scale of observation (i.e. pixel resolution) fails to correspond to the spatial characteristics of the target.

Remote sensing need in situ data





An overview of 21 global and 43 regional landcover mapping products

George Grekousis, Giorgos Mountrakis & Marinos Kavouras

To cite this article: George Grekousis, Giorgos Mountrakis & Marinos Kavouras (2015) An overview of 21 global and 43 regional land-cover mapping products, International Journal of Remote Sensing, 36:21, 5309-5335, DOI: <u>10.1080/01431161.2015.1093195</u>

To link to this article: http://dx.doi.org/10.1080/01431161.2015.1093195

Current global land cover data: http://worldgrids.org/doku.php/wiki:land cover and land use



Figure 2. Regional LC products count by location. Names of LC products per region along with the reference year in parenthesis are also included. Europe, China, and the USA offer a plethora of LC products for multiple reference years especially during the decade 2000–2010. Asia and Africa do not have a complete regional product solely developed for these regions. East Africa is only covered from Africover and Asia is covered sparsely by national efforts.
Understanding and monitoring LC distribution and dynamics are important factors in environmental studies. Updated LC information is essential for governments, non-governmental organizations, and other stakeholders assisting in the development and implementation of environmental policies for a sustainable future.

 For this reason, it is essential that LC products are as accurate and reliable as possible so that the outcomes are reliable and consistent. In reality though, because of the wide differences in the methodological approaches for each product (e.g. classification schemes, classification techniques, time of data acquisition, spatial resolution), there is often poor agreement among different data sets when applied at the regional or global level



International Journal of Digital Earth



ISSN: 1753-8947 (Print) 1753-8955 (Online) Journal homepage: http://www.tandfonline.com/loi/tjde20

A global, high-resolution (30-m) inland water body dataset for 2000: first results of a topographic–spectral classification algorithm

Min Feng, Joseph O. Sexton, Saurabh Channan & John R. Townshend

To cite this article: Min Feng, Joseph O. Sexton, Saurabh Channan & John R. Townshend (2016) A global, high-resolution (30-m) inland water body dataset for 2000: first results of a topographic–spectral classification algorithm, International Journal of Digital Earth, 9:2, 113-133, DOI: <u>10.1080/17538947.2015.1026420</u>

Link to data: http://glcf.umd.edu/data/watercover/

Single thematic products dedicated to only one LC class (Often forest or water)



Available Data - Water

- https://global-surface-water.appspot.com/download
- http://www.nature.com/nature/journal/v540/n7633/full/nature2058
 4.html
- Different download mechanisms (web, WMS,...)

DEM

SRTM (Shuttle Radar Topography Mission)

- <u>https://earthexplorer.usgs.gov/</u>
- https://lta.cr.usgs.gov/SRTM1Arc





The Shuttle Radar Topography Mission (SRTM) is an international research effort that obtained digital elevation models on a **near-global scale** from 56° S to 60° N. SRTM consisted of a specially modified radar system that flew on board the Space shuttle Endeavour during the **11-day mission in February 2000**. To acquire topographic data, the SRTM payload was outfitted with two radar antennas.

1-arc second global digital elevation model (30 meters) is available

DEM

TanDEM-X

- https://tandemx-science.dlr.de/

- <u>http://www.dlr.de/rd/en/desktopdefault.aspx/tabid-</u> 2440/3586 read-16692/





The approximately 150 million square kilometres of land surface were scanned from space. The use of radar technology based on two satellites orbiting in close formation is still unique and was key to the high-precision remapping of Earth.

It is a Public Private Partnership project operated in conjunction with Airbus Defence and Space. DLR is responsible for providing TanDEM-X data to the scientific community, mission planning and implementation, radar operation and calibration, control of the two satellites, and generation of the digital elevation model.

Access to the TanDEM-X Digital Elevation Model (DEM) is restricted – DLR supplies the data free of charge to scientific projects.









Radar vs. Lidar

DTM – Terrain attributes

Primary Attributes

- Slope
- Aspect
- Plan and Profile Curvature
- Hillshade
- Flow direction

Secondary Attributes

- Flow accumulation

http://desktop.arcgis.com/en/arcmap/10.3/tools/spatial-analyst-toolbox/how-slope-works.htm

🔨 Slope		— D	×
Input raster	•	Slope	~
Output raster	3	ldentifies the slope (gradient, or rate of maximum change in z-	
Output measurement (optional) DEGREE	~	value) from each cell of a raster surface.	
Z factor (optional)	1		

Slope ArcGIS vs QGIS

Skion		1
Parametry Záznam	Spustit jako dávkový proces	Slope
Vstupní vrstva	^	This algorithm is based on the GDAL gdalde
Číslo pásma	▼	For more info, see the module help
1		
Vypočítat hrany		
Použít vzorec Zevenbergena&Thorna (místo Hornova)		
Slope expressed as percent (instead of degrees)		
Měřítko (poměr svislých a vodorov. jednotek)		
1,000000	▲	
Sklon		
[Uložit do dočasného souboru]		
X Open output file after running algorithm		
Volání GDAL/OGR konzole.		
Neplatná hodnota pro parametr 'Vstupní vrstva'		

DTM – Terrain attributes (scale effects)



 $\beta_1 = (554 \text{ m} - 528 \text{ m}) \times 100\% / 30 \text{ m} = 87\%, \beta_1 \text{ is the slope gradient for X at 30-m spatial resolution, pointing from A₁ to A₂$ $<math>\beta_2 = (578 \text{ m} - 560 \text{ m}) \times 100\% / 90 \text{ m} = 20\%, \beta_2 \text{ is the slope gradient for X at 90-m spatial resolution, pointing from B₁ to B₂$ $<math>\beta_3 = (586 \text{ m} - 584 \text{ m}) \times 100\% / 150 \text{ m} = 1\%, \beta_3 \text{ is the slope gradient for X at 150-m spatial resolution, pointing from C₂ to C₁$

Y. Deng , J. P. Wilson & B. O. Bauer (2007) DEM resolution dependencies of terrain attributes across a landscape, International Journal of Geographical Information Science, 21:2, 187-213, DOI: 10.1080/13658810600894364





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Towards a framework for terrain attribute selection in environmental studies



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ABSTRACT

Terrain attributes (e.g. slope, rugosity) derived from digital terrain models are commonly used in environmental studies. The increasing availability of GIS tools that generate those attributes can lead users to select a sub-optimal combination of terrain attributes for their applications. Our objectives were to identify sets of terrain attributes that best capture terrain properties and to assess how they vary with surface complexity. 230 tools from 11 software packages were used to derive terrain attributes from nine surfaces of different topographic complexity levels. Covariation and independence of terrain attributes were explored using three multivariate statistical methods. Distinct groups of correlated terrain attributes were highly covarying and sometimes ambiguously defined within software documentation. We found that a combination of six to seven particular terrain attributes always captures more than 70% of the topographic structure of surfaces.





Thank you for attention!

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